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Action minimization and
global continuation of
Lyapunov families stemming
from relative equilibria.

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COLLABORATION WITH Jacques FÉJOZ

N-body problem in \mathbb{R}^3

$$\ddot{\vec{r}}_i = \sum_{j \neq i} \frac{m_j (\vec{r}_j - \vec{r}_i)}{\|\vec{r}_j - \vec{r}_i\|^3}$$

$i = 1, \dots, N$

SYMMETRIES

● ISOMETRIES of \mathbb{R}^3



Relative equilibrium solutions
(necessarily planar) ← easy

● SCALING :

if $x(t) = (\vec{r}_1(t), \dots, \vec{r}_N(t))$ solution,
also, $\lambda^{-2/3} x(\lambda t)$ solution



Homographic solutions
(necessarily planar) ← less easy

● PERMUTATIONS OF EQUAL MASSES



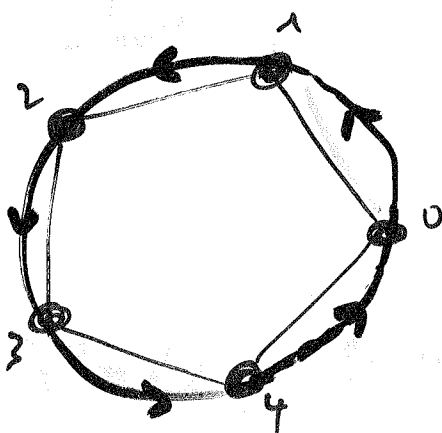
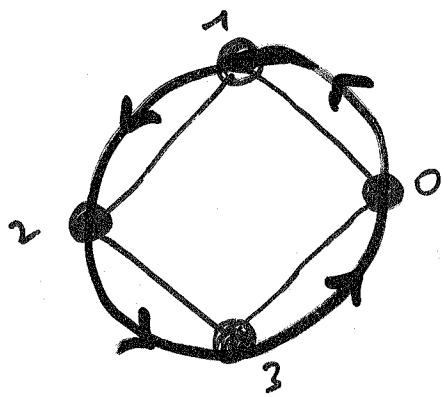
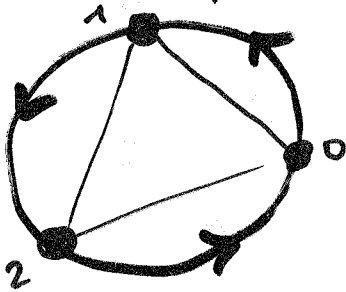
Solutions minimizing action

$$\int_0^T \left(\underbrace{\frac{1}{2} \sum_i m_i |\dot{\vec{r}}_i(t)|^2}_K + \underbrace{\sum_{i < j} \frac{m_i m_j}{\|\vec{r}_i(t) - \vec{r}_j(t)\|}}_U \right) dt$$

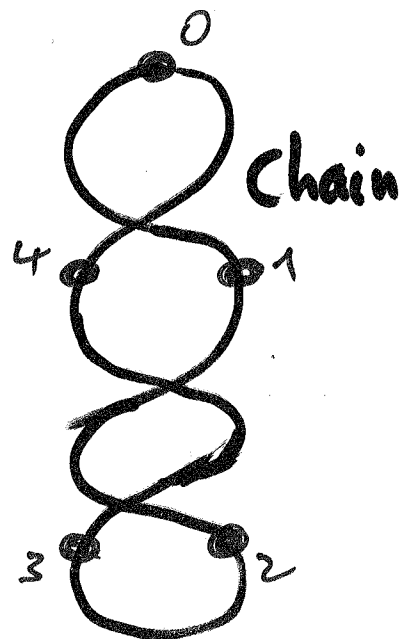
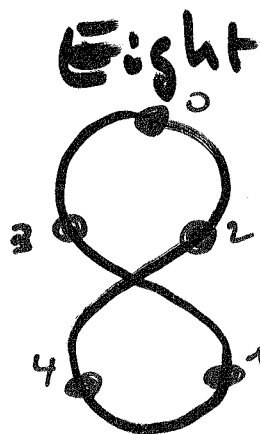
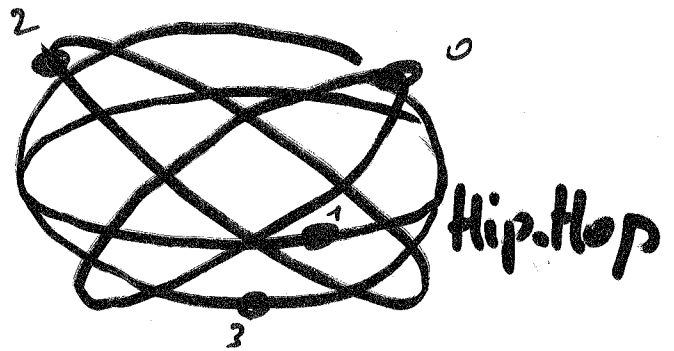
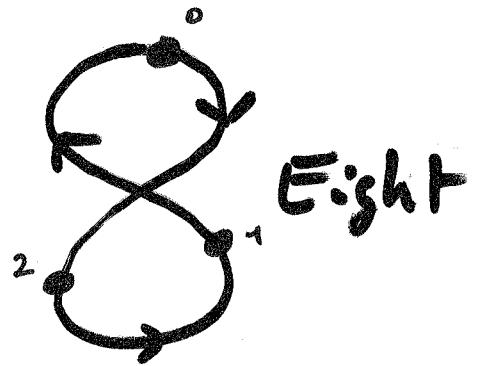
under symmetry constraints

FACT: \exists strong relation between

Simplest R.E.
 Regular N-gon
 with N equal masses

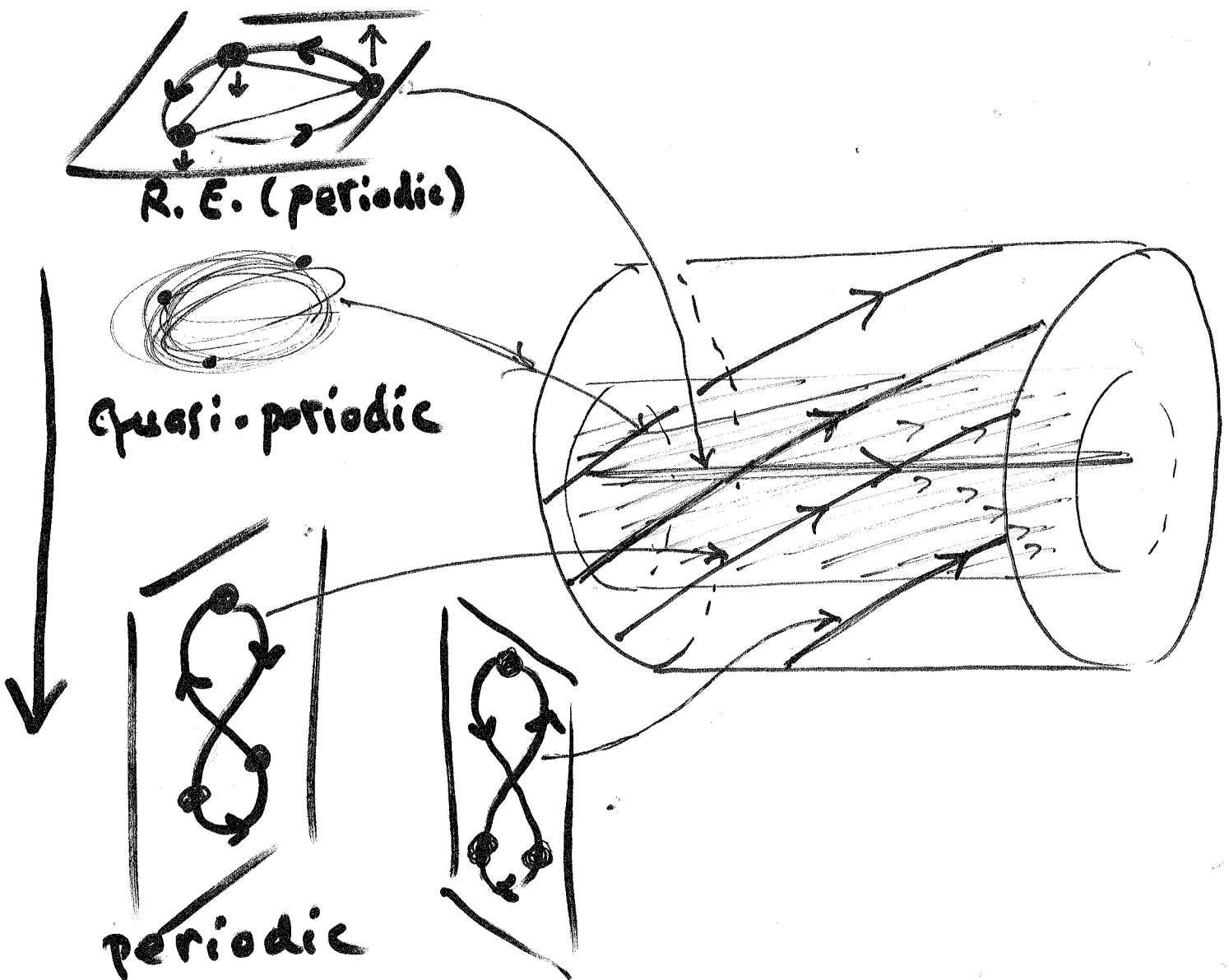


Simplest
 action minimizing
 solutions:



ORIGIN: (first discovered
by C. Marchal for 3 bodies)

Vertical Lyapunov families
stemming from horizontal
Relative equilibrium



E. MARCHEL
The three-body
problem.

1990

t at the tip of the eles triangle
A
B
C
A
B
C

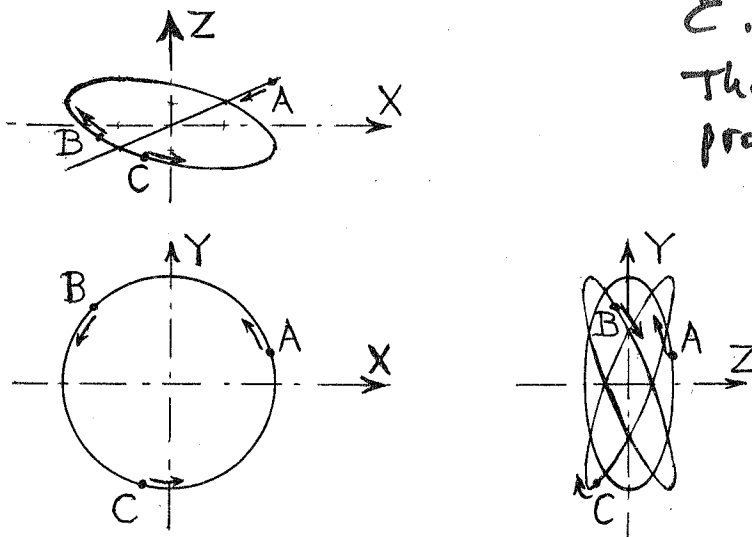


Fig. 78. Symmetric-periodic orbits with twelve space-time symmetries per period.

The three main projections of the orbits of A,B and C for small values of c_1 and t .

These almost circular orbits rotate very slowly about the Z-axis because of the small "angle of rotation".

For large c_1 the series (779)-(795) are of course less accurate and can no longer be used. However the periodic orbits of the family retain their twelve space-time symmetries per period and it would be interesting to look numerically for their evolution up to termination.

Notice that this termination is sometimes surprising as we will see in Section 10.9.1 for the family of retrograde pseudo-circular orbits that ends into rectilinear orbits !

10.8.3 The Halo orbits about the collinear Lagrangian points.

The Halo orbits are a family of simple periodic orbits of the circular restricted three-body problem. these orbits remain in the vicinity of a collinear Lagrangian point and are among the most useful orbits for many types of missions (Fig. 79). They have already been presented in Section 9.1 and in Fig. 24.

are expressed
an formulation
of c_1 :

(798)

(799)

(800)

related to the

(801)

5.2 and using
to order four
th $T = 2\pi$ and

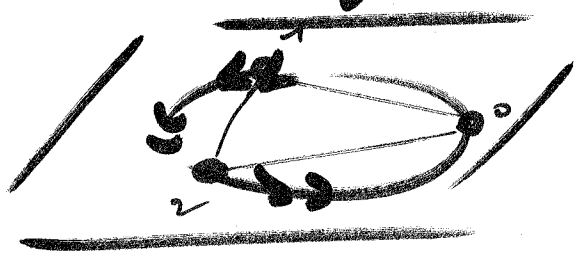
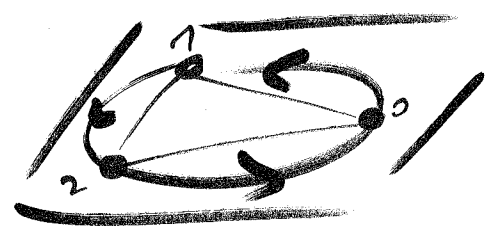
circular, with
ascending nodes

because of the

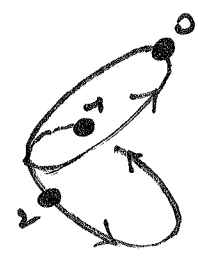
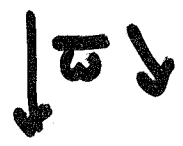
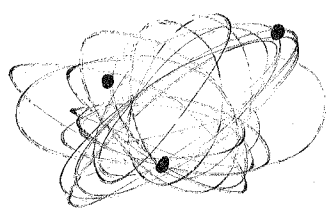
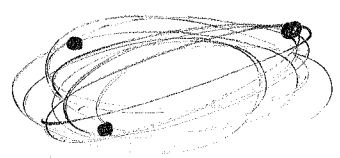
KEY : Start with very symmetric R.E. (ex regular N-gon, N equal masses):

Quasi-periodic in inertial frame

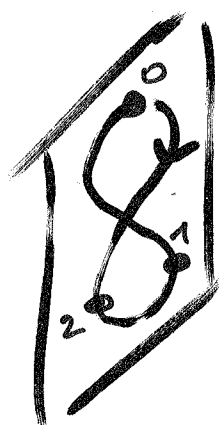
Periodic with huge symmetry in rotating frame



ROTATING FRAME



$\omega = 0$



(In this case: D_6 symmetry)

3 STEPS

— INFINITESIMAL :

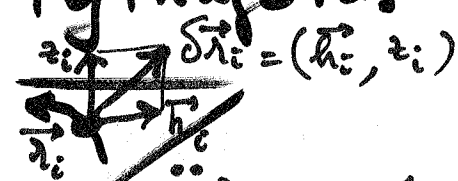
VVE, Symmetries
of solutions in rotating
frames.

== LOCAL : Bifurcation of
vertical Lyapunov families:
existence, unicity

≡ GLOBAL : Continuation of
local families via
(local) minimization under
symmetry constraints.

The vertical variational equation (VVE)

Pythagoras \Rightarrow splitting of VE



$$\delta \vec{x}_i = (\vec{h}_i, z_i)$$

$$\left. \begin{array}{l} \text{HVE} \\ \text{WE} \end{array} \right\} \begin{array}{l} \ddot{\vec{h}}_i = \sum_{j \neq i} m_j \frac{\vec{h}_j - \vec{h}_i}{\|\vec{x}_j - \vec{x}_i\|^3} - 3 \sum_{j \neq i} m_j \frac{\langle \vec{x}_j - \vec{x}_i, \vec{h}_j - \vec{h}_i \rangle}{\|\vec{x}_j - \vec{x}_i\|^5} (\vec{x}_j - \vec{x}_i) \\ \ddot{z}_i = \sum_{j \neq i} m_j \frac{z_j - z_i}{\|\vec{x}_j - \vec{x}_i\|^3} \end{array}$$

\downarrow constant for a R.E.

VVE of R.E. $\ddot{\vec{z}} = \mathbf{W} \vec{z}$

(Symmetric for the "mass scalar product"
 $\leftarrow 0$ after quotient by translations
 $(\Leftrightarrow \text{fix } \sum m_i z_i = 0)$)

$\Rightarrow \exists$ basis of eigenvectors $Z_1, \dots, Z_{N-1} \rightarrow \uparrow$
 with eigenvalues $-\omega(1)^2 \dots -\omega(N-1)^2$

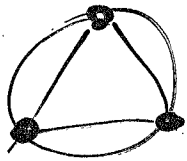
General solution:

$$Z(t) = \sum_{k=1}^{N-1} \text{Re} \left(\underbrace{\alpha_k}_{\text{"}} Z_k e^{i\omega(k)t} \right)$$

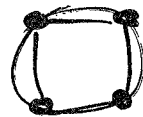
W_k complex eigenvector of W with eigenvalue $-\omega(k)^2$

Solutions of VVE (regular N-gon)

After reduction of Fraustekens, phase space of VVE has dim $2(N-1)$
 (OPS $\sum_{i=0}^{N-1} z_i = 0$ and $\sum_{i=0}^{N-1} \dot{z}_i = 0$)



$$N = 2m + 1$$



$$N = 2m$$

Phase space = $\bigoplus_{k=1}^m$ of m 4-dim spaces

Phase space = $\bigoplus_{k=1}^m$ of $\begin{cases} m-1 & 4\text{-dim space} \\ 1 & 2\text{-dim space} \end{cases}$

if $N = 2m + 1$ $\lambda_k = -2 \sum_{j=1}^m \frac{1}{f_j^3} \left(1 - \cos \frac{2\pi j k}{N}\right) = -\omega_k^2$

if $N = 2m + 2$, idem $-\frac{1}{f_{m+1}^3} (1 - (-1)^k)$.

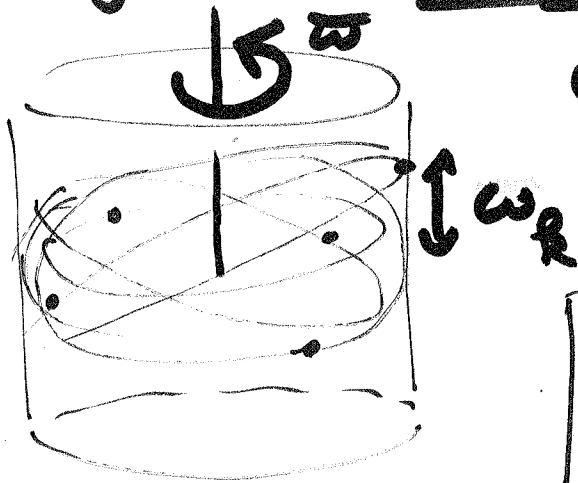
$(f_j = |z^j - 1|, z = e^{\frac{2\pi i}{N}})$

Proposition: $\omega_1 < \omega_2 < \dots < \omega_m < \dots$

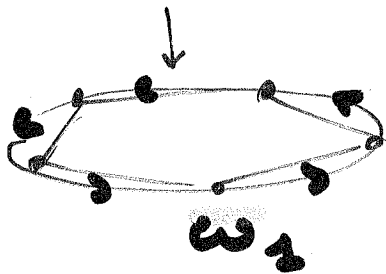
I $(\text{Re}(e^{i\omega_1 t}), \text{Re}(f^k e^{i\omega_1 t}), \dots, \text{Re}(f^{k(N-1)} e^{i\omega_1 t}))$

II $(\text{Re}(e^{i\omega_2 t}), \text{Re}(f^k e^{i\omega_2 t}), \dots, \text{Re}(f^{k(N-1)} e^{i\omega_2 t}))$

Symmetries of 1st order solutions in rotating frame



$$\bar{\omega} = \omega_1 - \gamma \omega_R$$



$$S_r(N, k, h) = \left(\underbrace{\sum_j^{\text{body}} e^{i\gamma \omega_R t}}_{\text{HORIZONTAL}}, \underbrace{\text{Re} \sum_{j=0, \dots, N-1}^{\pm 1} z^{kj} e^{i\omega_R t}}_{\text{VERTICAL}} \right)$$

$(z_j \in \mathbb{C}/N\mathbb{Z})$

$\frac{2\pi s}{\omega_R}$ periodic $\Leftrightarrow \delta = \frac{2}{s}$ (dense).

OPS = 1
(time scale)

$$\vec{r}_j(t) = \rho \vec{r}_{\xi(j+\delta)}(\xi(t-\theta))$$

$\xi = \pm 1 (\in \mathbb{F}_2)$, $\delta \in \mathbb{Z}/N\mathbb{Z}$, $\theta \in \mathbb{R}/1\mathbb{Z}$

$$\rho(H, V) = (e^{2\pi i \alpha} \bar{H}^\xi, e^{i\pi \beta} V)$$

$\beta \in \mathbb{Z}/2\mathbb{Z}$, $\bar{H}^\xi = H$ if $\xi = +1$, \bar{H} if $\xi = -1$

with $\begin{cases} \alpha = \frac{2}{s} \theta - \frac{\delta}{N} \pmod{1} \\ \theta = \frac{\beta}{2} + k \frac{\delta}{N} \pmod{1} \end{cases} (\Rightarrow s \text{ values})$

Identification of the symmetry group $G_{\frac{2}{s}}(N, k, b)$

It is the subgroup of

$$\left(\mathbb{R}/s\mathbb{Z} \times \mathbb{Z}/N\mathbb{Z} \times \mathbb{Z}/2\mathbb{Z} \right) \rtimes \mathbb{F}_2$$

θ δ β ξ

[group law $(\theta', \delta', \beta', \xi') \cdot (\theta, \delta, \beta, \xi) = (\theta' + \xi'\theta, \delta' + \xi'\delta, \beta' + \beta, \xi'\xi)$]

defined by the equation

$$\theta = \frac{\beta}{2} + kb \frac{\delta}{N} \pmod{1}$$

Example: ($s=1$)

$$G_2(N, k, b) \cong D_N \times \mathbb{Z}/2\mathbb{Z}$$

($\cong D_{2N}$ if N odd)

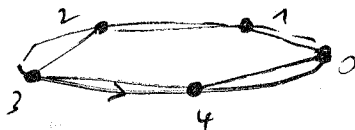
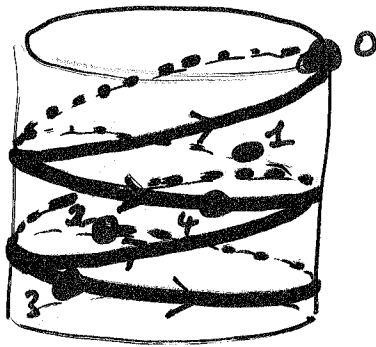
Examples : (1) chortographies

$$N = 2n + 1$$

$$\frac{1}{2} = N - 1$$

$$k = 1$$

$$h = -1$$



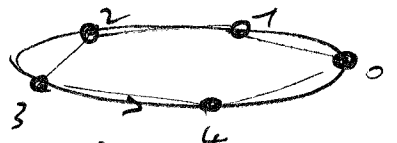
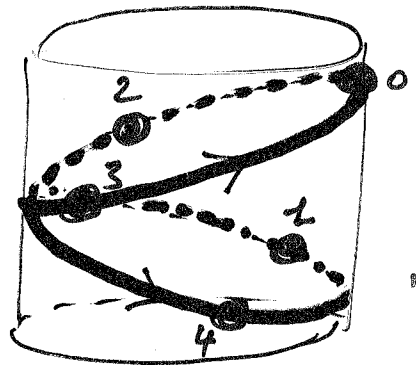
CHAINS

$$N = 2n + 1$$

$$\frac{1}{2} = 2$$

$$k = n$$

$$h = -1$$



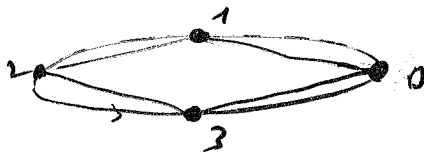
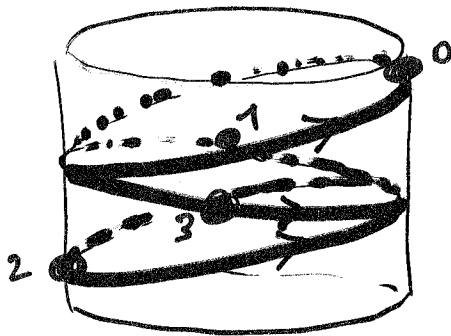
EIGHTS

$$N = 4$$

$$\frac{1}{2} = 3$$

$$k = 1$$

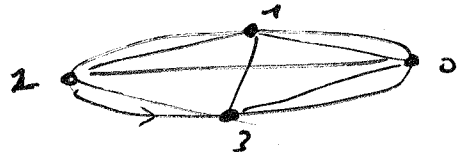
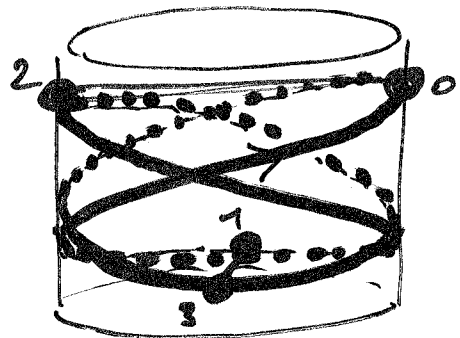
$$h = -1$$



$$N = 4$$

$$\frac{1}{2} = \frac{3}{2}$$

$$k_2 = 2$$

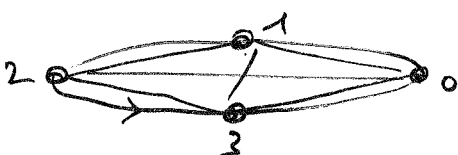
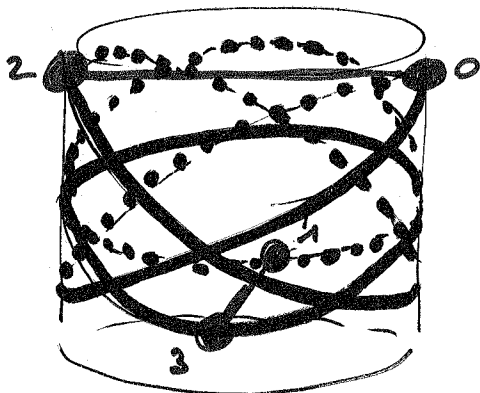


(2) Hip-Hops

$$N = 2n$$

$$\frac{1}{2} = 1$$

$$k_2 = n$$



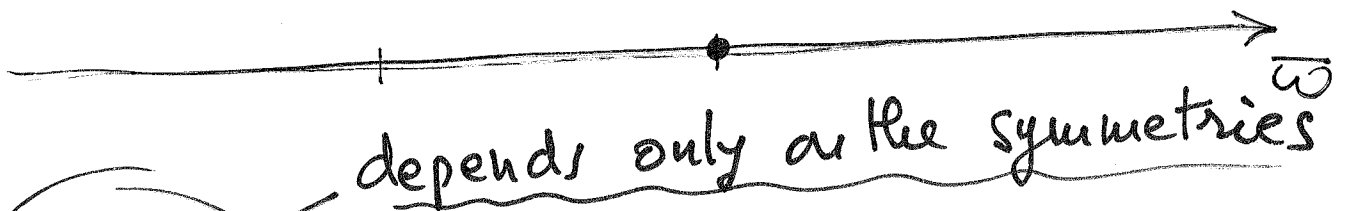
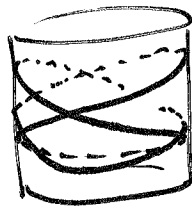
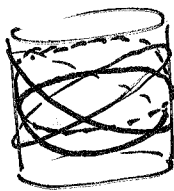
etc ...



Remark : N, k, h given,

$\left\{ \underline{\omega} = \omega_1 - \frac{2}{s} \omega_k, S_{\frac{2}{s}}(N, k, h) \right\}$
 is a simple choreography
 (1. curve)

is dense in \mathbb{R}



depends only on the symmetries

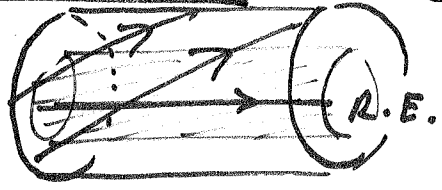
Proof: $\Leftrightarrow \exists g \in G_{\frac{2}{s}}(N, k, h),$
 $s=1, \delta \neq 0, \alpha=0, \beta=0$
 $(\delta, N) = 1$ (simple)

$\Leftrightarrow \begin{cases} (r, s) = 1 \\ s - k h r = 0 (N) \end{cases}$

then easy ... 3 lines

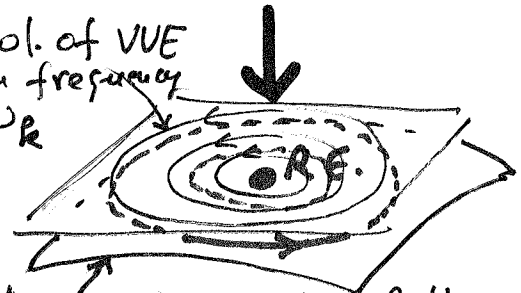
= Local Lyapunov families

Reduction of isometries:



- fix center of mass
- angular momentum

→ sol. of VUE with frequency ω_R



- quotient by $SO(2)$



eliminates a pair of $\pm i\omega_R$ (one H, one V)

Lyapunov periodic solutions of frequency close to ω_R (invariant surface in reduced phase space)

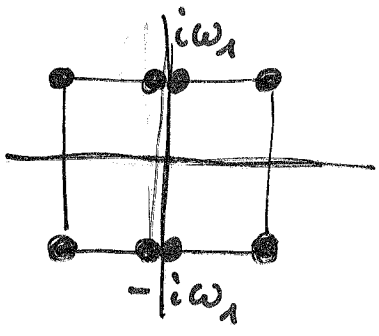
$\dim \delta N - 10$

$4N - 6$ HORIZONTAL

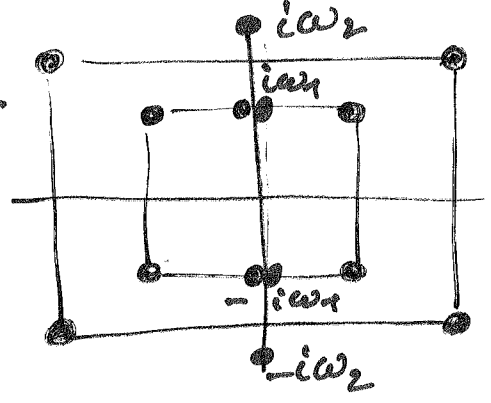
$2N - 4$ VERTICAL

Problem: Spectrum very resonant!

$N=3$



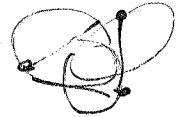
$N=4$



For $N \geq 6$, there appears new horizontal purely imaginary eigenvalues!

$N=3$ (A.C. & J. Fejos 2006
 ω_1 see also Marchal's book 1990)

Using normal folius



\exists exactly 2
 Lyapunov families
 (same frequency ω_2)

- 1 HORIZONTAL: Homographic family
- 1 VERTICAL: P_{12} family,
 D6 symmetric, containing the δ .



$N=2n$
 ω_n

(E. Barabés
 JM Cors
 C Pinjol 2006
 J. Soler

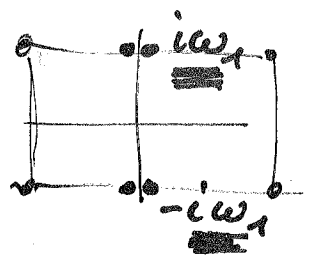
see also
 K. Meyer & D. Schmidt (1993
 (with 2 central mass).

\exists and \neq of the corresponding Lyapunov
 family (Hip-Hop).

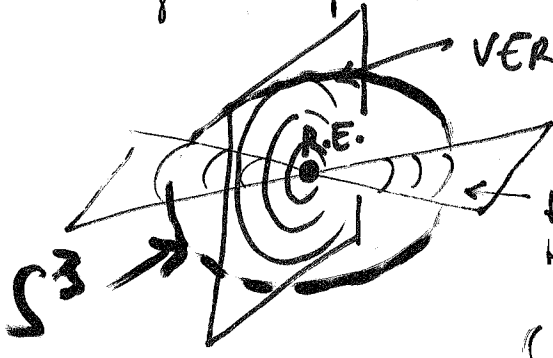
CASES FOR WHICH A PROOF IS AVAILABLE

$N=3$ (A.C. & J. Fej'03) : see also Marchal's book
2006

in Center manifold of dim 4,
energy surface $\cong S^3$

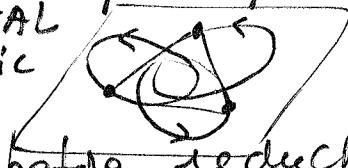


Normal forms have resonance at any order
along homographic family. Still one can
have \exists exactly 2 Lyapunov families
originating from the Lagrange equilateral R.E.

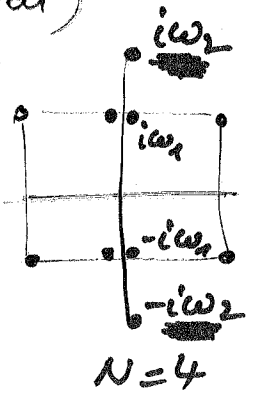


VERTICAL FAMILY WITH D6 SYMMETRY
(Marchal's P12 family)
quasi-periodic before reduction

HORIZONTAL
HOMOGRAPHIC
FAMILY
(periodic before reduction)



$N=2n, P_2=n$ (E. Barrabés)
(Hip-Kop symmetry) (J.M. Cors)
(C. Pignol) 2006
(J. Soler)



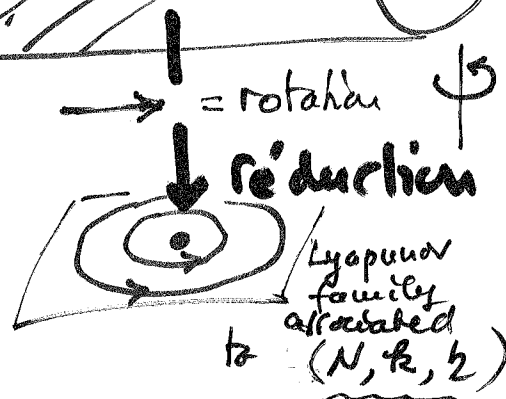
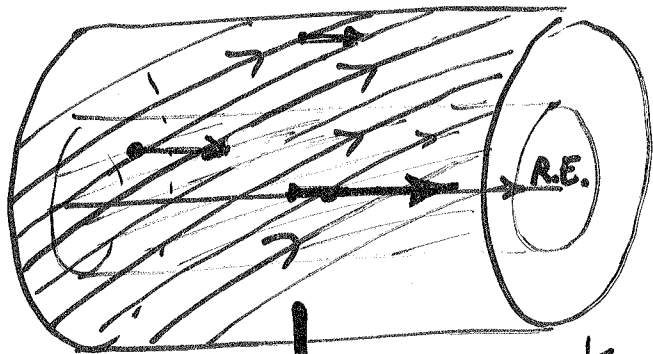
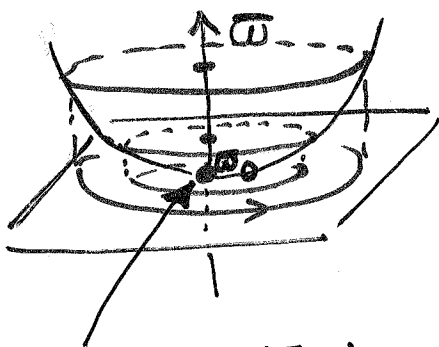
These authors prove the existence
of the Lyapunov families by analytic
continuation. See also similar
case by K. Meyer & D. Schmidt (1993)
when \exists central mass (model for
Saturn braided rings).



Global continuation via minimization under symmetry constraint

Periodic solutions
of the reduced problem

\Updownarrow
Periodic solutions in
rotating frame



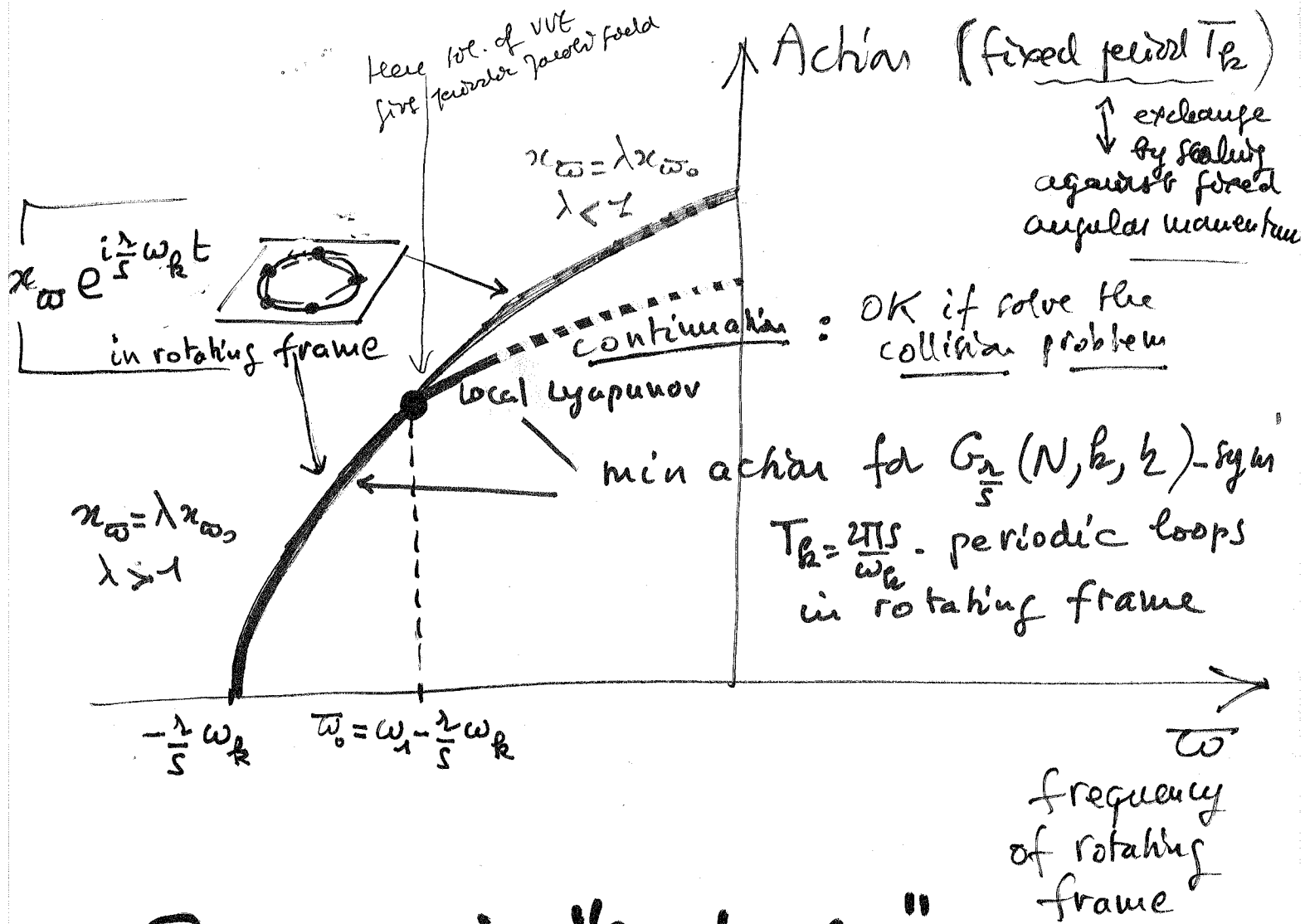
Necessarily $\exists \frac{\lambda}{s} \in \mathbb{Q}$, $\bar{\omega}_0 = \omega_1 - \frac{\lambda}{s} \omega_k$

If 1! \Rightarrow family of $G_{\frac{\lambda}{s}}(N, k, h)$. Symmetric (in rotating frame)

$\frac{2\pi s}{\omega_k}$ - periodic solutions parametrized by $\bar{\omega}$.

// Look for such a family
as a family of ^(local) ∇ action minimizers

Why is this reasonable?



Because in "good cases" one has the above situation.

not minimizing: \sum eigenvalues of $W(x_{\omega_0}) \rightarrow -\omega_h^2$

$$d^2 A \left(\underset{\lambda x_{\omega_0}}{x_\omega e^{i \frac{\lambda}{5} \omega_R t}} \right) (z, z) = \underbrace{\int_0^{T_h} \frac{1}{2} \|\dot{z}\|^2 dt}_{+ \omega_h^2 \int_0^{T_h} \frac{1}{2} \|z\|^2 dt} + \underbrace{\int_0^{T_h} d^2 U(x_\omega)(z, z) dt}_{- \frac{1}{\lambda^2} \omega_h^2 \int_0^{T_h} \|z\|^2 dt}$$

$$> 0 \Leftrightarrow \lambda > 1$$

$$< 0 \Leftrightarrow \lambda < 1$$

Remark :

$G_{\frac{2}{S}}(N, k, h)$ symmetry in
rotating frame with frequency ω

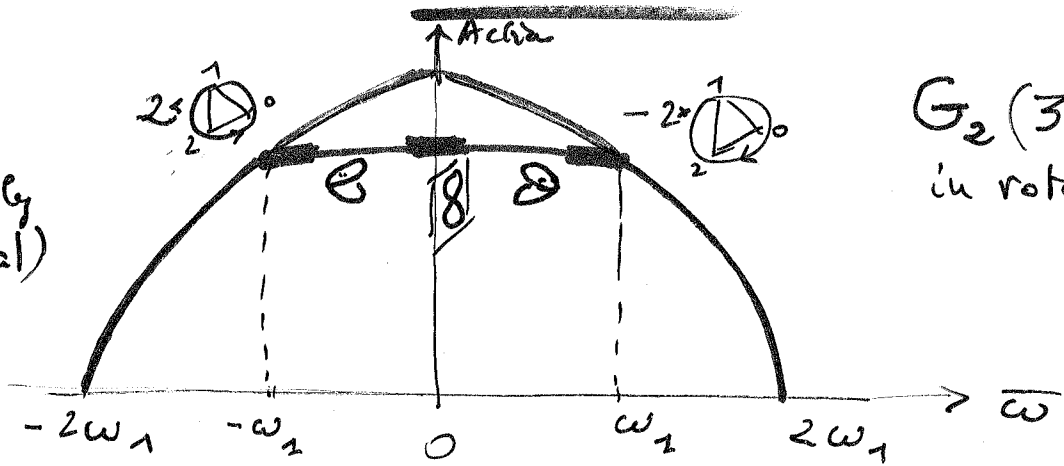
$$\Downarrow \quad \alpha \Rightarrow \alpha + \omega \theta$$

$G_{\frac{2}{S} + \omega}(N, k, h)$ symmetry in
inertial frame.

Corollary : choreographies
dense in ^(vertical) Lyapunov families

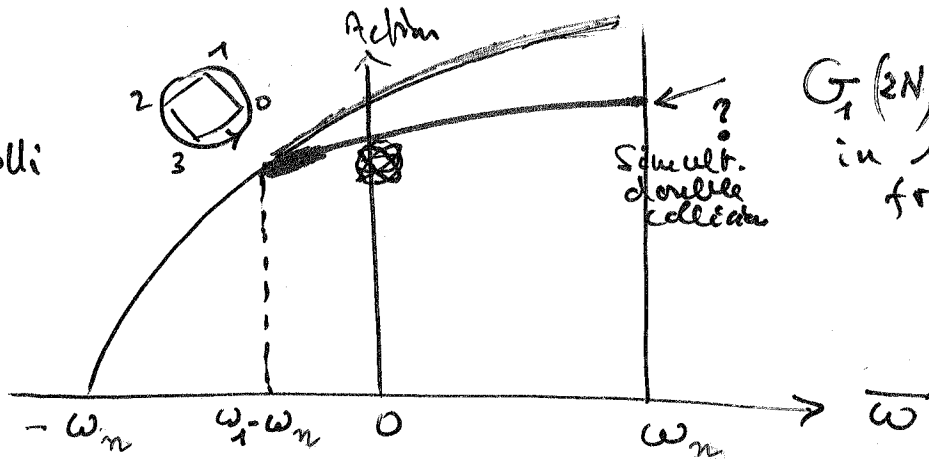
EXAMPLES

$N=3$
 P12 family
 (Nardal)



$G_2(3, 1, -1)$
 in rotating frame

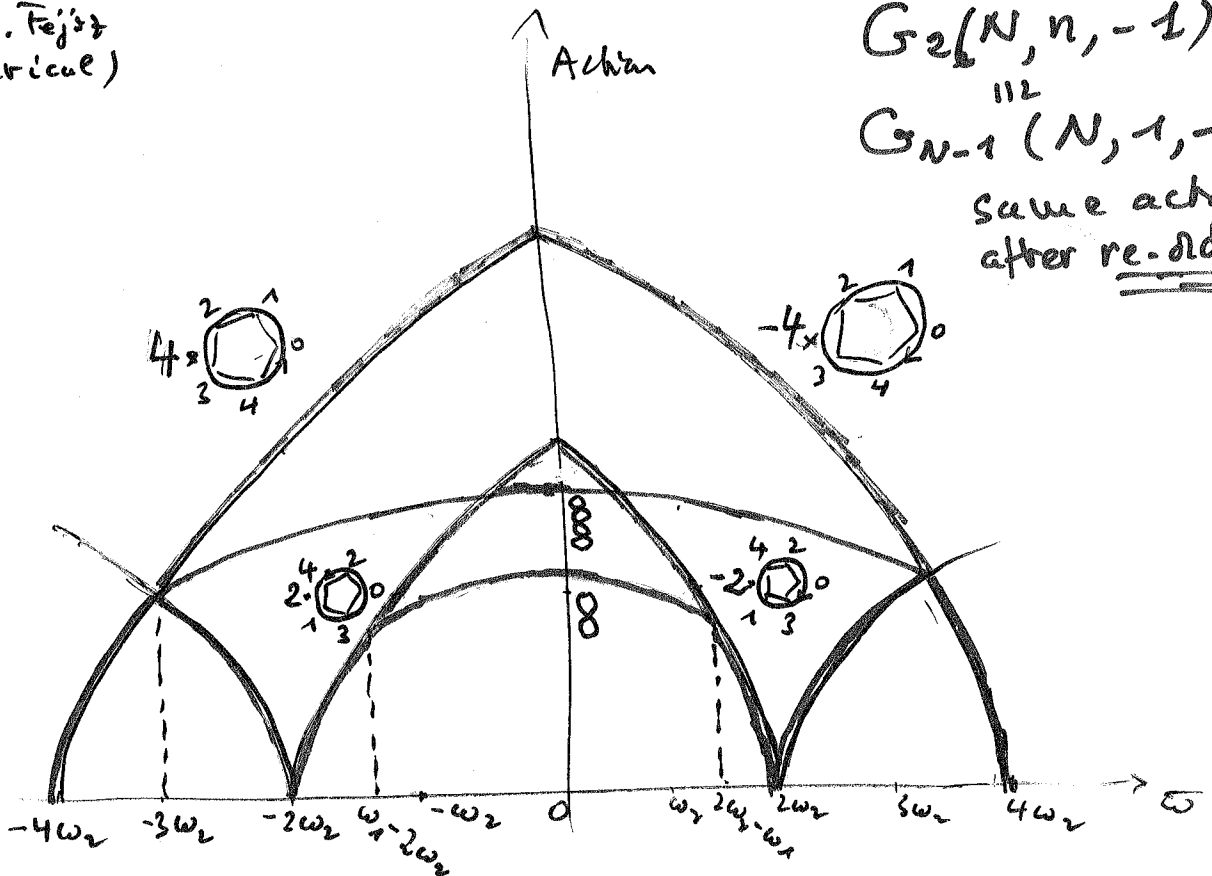
$N=2N$
 Hip. Hop family
 Terracini-Venturelli



$G_1(2N, n, 1)$
 in rotating frame

Simult.
 double
 collision

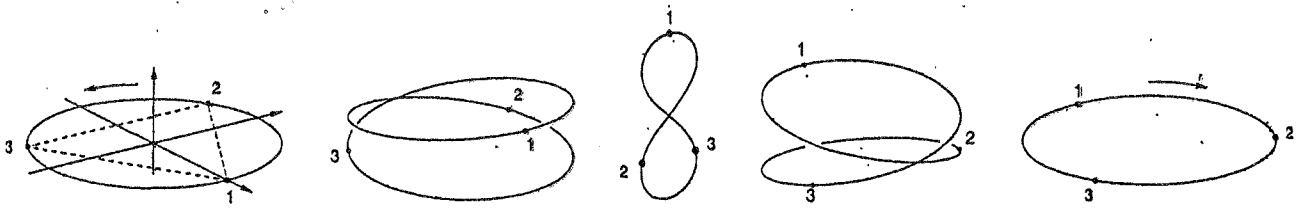
$N=5$
 Chencine-Fejz
 (numerical)



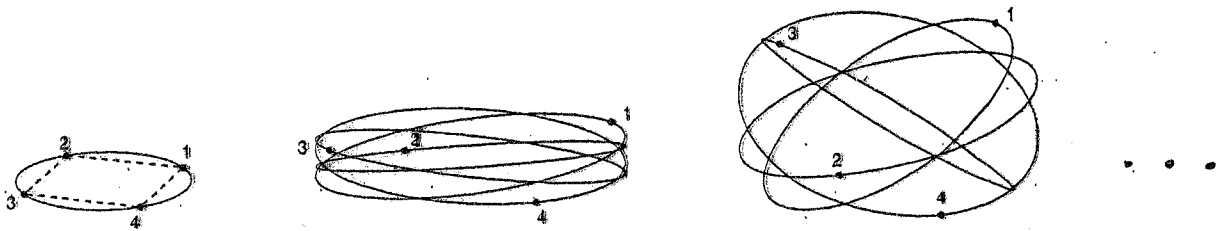
$G_2(N, n, -1)$

$G_{N-1}(N, 1, -1)$

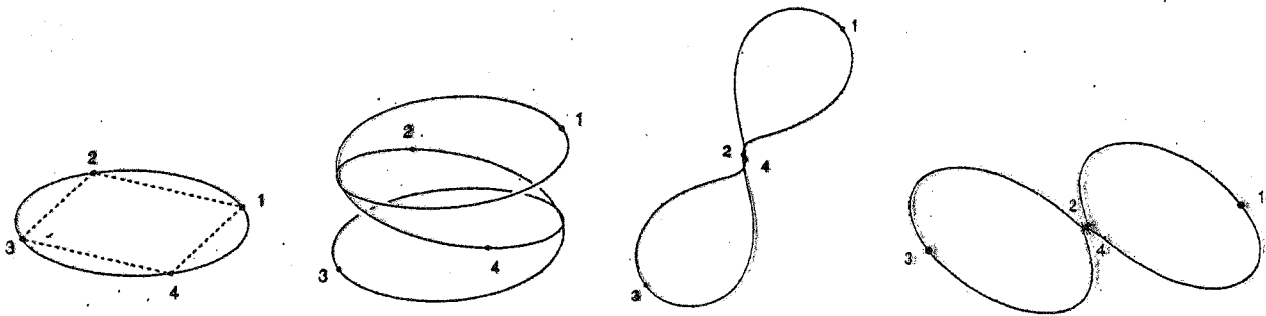
same action
 after re-ordering



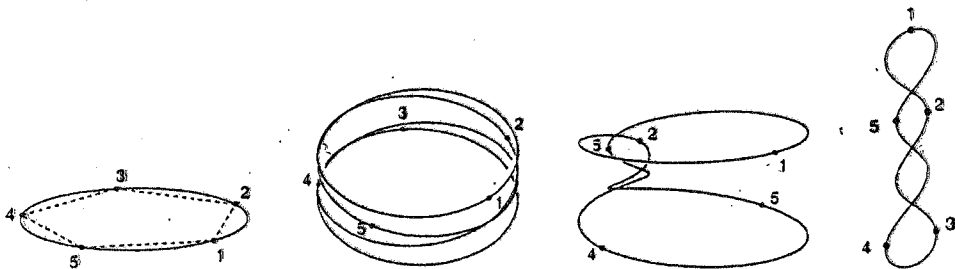
FROM EQUILATERAL TO EIGHT - THE P12 FAMILY



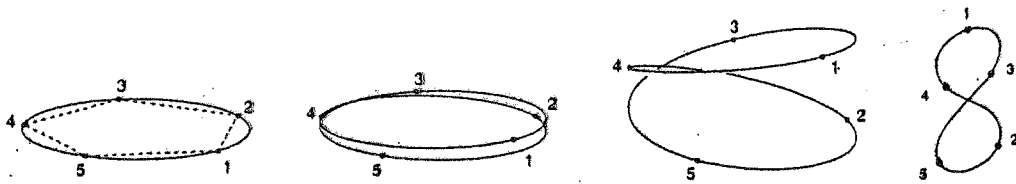
THE HIP-HOP FAMILY



4 BODIES : THE FIRST VERTICAL FREQUENCY



FROM PENTAGON TO 4.CHAIN



FROM PENTAGON TO EIGHT